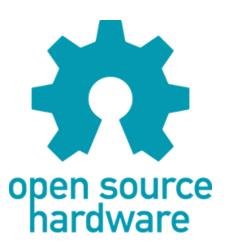


# Train the Trainer Programme









**Industrial Automation** 



Medical & HealthCare



**Smart Agriculture** 



**Mobility & Transportation** 



**Smart City Applications** 

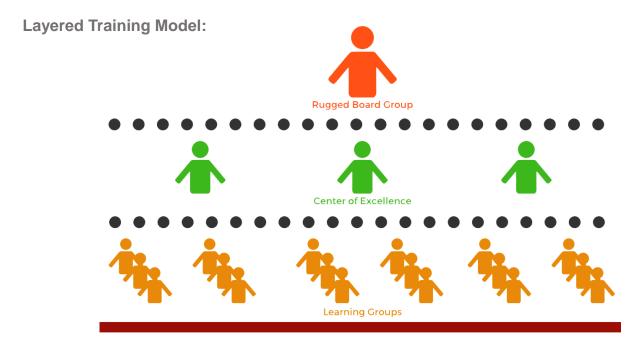


RuggedBoard is an Industrial grade IoT board developed by PHYTEC Embedded Pvt. Ltd Make In INDIA with German Quality. It is the first of its kind Industrial IoT Single Board Computer with multiple interfaces required for IIoT applications in Industry-4.0, Smart Cities, Smart Transportation, Smart Energy & Smart Agriculture. This IoT project would build big Hardware ecosystem in INDIA and support Industries to develop their own IoT products & manufacture in INDIA with ease.

To promote MAKE IN INDIA & Aatmanirbhar Bharat by developing Products & Technology IP's in INDIA and bringing in University partners to hold major role in research & development, PHYTEC team would like to share the technical expertise with Trainer members from University & together solve real-time industry problems and also bring in more innovations with latest technologies from University Labs.

### **Stages of Learning & Development:**







Level-1 Train the Trainer Programme		
Building Embedded Linux System		
Module-1: Linux Basics & Programming ( 2 Days)		
Linux Intro & Installation	- What is Linux, how it has been evolved, GNU License, Kernel	
	- How Linux was designed,	
	- Sub systems of Linux [ Scheduler, Process, Memory Mgmt, File	
	System, Device Mgmt]	
	- Ways to Install Linux [1. Dual Boot, 2. Within Windows, 3. Using	
	Virtual Machine ]	
Linux Shell Commands	- How to update Linux and install required packages - Basic Commands	
Linux Shell Commands	- Dir & File Commands	
	- System Commands	
	- Misc Commands	
C Programming in Linux	- Writing C program on Linux	
	- Compiling and executing Linux	
	- Linux Executable format info & tools	
	- Debugging C application on Linux using GDB	
	- MQTT Experiments	
Make Files	- Understanding Make files	
	- Writing Make files	
	- Compiling Multiple src Dir using Make file	
	- Advanced methods used in writing Make files	
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Module-2: eLinux Portin		
Introduction, Setup & Hardware	- Introduction to Embedded Linux - ARM Processor Basics & Families	
nardware	- ARM Processor Basics & Families  - ARM Board Details and Schematic Overview	
	- Boot Process	
	- Host PC Setup for eLinux Development	
Bootloader U-Boot Porting	- Toolchain and its components	
<b>3</b>	- Introduction to Bootloader	
	- Compiling Bootloader	
	- How to port Bootloader on ARM Based Hardware	
Kernel Porting &	- Introduction to Linux Kernel Arch	
Compilation	- Kernel Dir Structure	
	- Kernel Build System ( KConfig )	
	- How to configure and compile for ARM Hardware	
Deal Elle Cod	- How to port Kernel on New ARM Hardware	
Koot File-System	•	
	''	
Root File-System	- Components of RootFS -Types of RootFS -Different types of Flash Device ( SDCARD / NOR ) - Test Your First Application - " Hello world " in SBC.	



# Level-2 Train the Trainer Programme Building Industrial IoT Applications using RuggedBOARD

RuggedBOARD		
Module-3: HW Interface	& Sensor Programming in eLinux (5 Days)	
Linux GPIO Programming	- Introduction to Linux GPIO SubSystem	
	- Accessing GPIO using Sysfs	
	- Programming GPIO's in C	
	- Programming GPIO's using MRAA Lib in C	
	- Programming GPIO's using MRAA Lib in PYTHON	
	- LEDs, Switches Experiments	
	- Relay Demo	
	- Seven Segment Demo	
Linux UART Programming	- Understanding Serial Port in Linux	
	- Programming UART using C	
	- Programming UART using MRAA Lib in C	
	- Programming UART using MRAA Lib in PYTHON	
	- GSM & GPS Experiments	
	- Bluetooth Demos	
	- RFID Card Read Demos	
	- RS485 ModBUS RTU Demo	
Linux ADC Programming	- Understanding ADC Subsystem in Linux	
	- Accessing ADC using SysFS	
	- Programming ADC using MRAA Lib in C	
	- Programming ADC using MRAA Lib in PYTHON	
	- ADC Experiments using Resistor POT.	
	- Temperature Sensor Interfacing Experiments	
Linux PWM Programming	- Understanding PWM Subsystem in Linux	
	- Accessing PWM using SysFS	
	- Programming PWM using MRAA Lib in C	
	- Programming PWM using MRAA Lib in PYTHON	
	- PWM Experiments & verify using Oscilloscope.	
	- Stepper Motor Interfacing Experiments	
	- LED Driver Interface Demo	
Module-4: Advance Sens	sor Interface Programming in eLinux ( 5 Days)	
Linux I2C Programming	- Understanding I2C Subsystem in Linux	
	- Programming I2C using MRAA Lib in C	
	- Programming I2C using MRAA Lib in PYTHON	
	- I2C MEMS Temp Sensor Experiment	
	- I2C Accelerometer Temp Sensor Experiment	
Linux SPI Programming	- Understanding SPI Subsystem in Linux	
	- Programming SPI using MRAA Lib in C	
	- Programming SPI using MRAA Lib in PYTHON	
	- SPI MEMS Sensor Experiment	
	- SPI Graphic OLED Interface Demo	
Linux Ethernet Socket	- Linux Network Socket Basics	



Programming	- TCP Client Server Experiments	
	- UDP Client Server Experiments	
	- HTTP REST API Cloud Experiment	
	- MQTT Cloud Experiment	
Linux CAN Socket	- Linux CAN Socket Basics	
Programming	- CAN Socket Programming	
	- CAN to DIO Card Interface Experiment	
	- EV Charger Control Card Demo	
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### **Module-5: Project-1 Guidance (5 Days)**

### Any one project of interest can be selected by the candidate

Smart Home Automation System

**Smart Irrigation System** 

Smart Street Light System using LoRA

Telematic Control Unit

# Module-5: Project-2 Guidance (5 Days)

### Any one project of interest can be selected by the candidate

Industry-4.0 Multi-Protocol Gateway Development

Industrial Energy Management System Gateway Development

Industry-4.0 HMI Development

Smart City Weather Monitoring Station Development

Smart Patient Monitoring System

## Complete Hands-On on INDIA's First Open Source Hardware "RuggedBOARD" Swadeshi Single Board Computer





A5D2x @500MHz CORTEX - A5 64MB RAM 32MB FLASH



2 x USB



DC & USB Power



EXPANSION HEADER



mikroBUS CONN.



mPCIe conn.





MICRO SIM SLOT

**RS-232** 2 x RS232 1x RS485

1 x CAN



1 x ETHERNET



TFT & CAP TOUCH



For More details visit:

https://community.ruggedboard.com